

Srikanth Malla

SUNNYVALE · CALIFORNIA · USA

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Research Interest

My passion is the quest for understanding and modeling visual intelligence in humans, particularly in applications involving behavior understanding, prediction, 3D scene modeling, and reasoning. The research problems that I would like to pursue include learning with limited data, generalizing concepts across different domains, and learning data representations without labels through unsupervised or weakly supervised methods. I would like to apply solutions to these problems in different domains, including intelligent mobility, 3D modeling, and robotics.

Education

Worcester Polytechnic Institute

Worcester, Massachusetts, USA

M.SC. ROBOTICS ENGINEERING, GPA: 4.0/4.0

Jan 2017 - Aug 2018

- **Honda Research Institute**, San Jose, CA — *Research Internship Program Spring, Summer 2018*

Vellore Institute of Technology

Vellore, India

B.TECH. IN ELECTRONICS AND INSTRUMENTATION, GPA: 8.79/10

July 2012 - May 2016

- **Carnegie Mellon University**, Pittsburgh, PA — *Semester Abroad Fall 2015, Spring 2016*

Research Experience

Kinetic Automation

Mountain View, California, USA

STAFF RESEARCH ENGINEER - MACHINE LEARNING

Mar 22-Present

Responsible for Machine learning related tasks simulation, data creation, algorithm design, and deployment.

RESEARCH ENGINEER

Oct 21-Feb 22

Developing 3D Machine Vision algorithms for Autonomous Driving and Electric Vehicles maintenance.

Honda Research Institute

San Jose, California, USA

RESEARCH ENGINEER

Sept 18-Oct 21

Worked on 3D detection using LiDAR, camera sensors and Joint 2D-3D Multi Object Tracking, action recognition, future trajectory forecast research topics. Sub-research topics include interaction modelling and important agent identification.

RESEARCH INTERN

Jan 18-Sept 18

Worked on 3D scene understanding research topics like 3D Mapping using LiDAR sensor and sensor fusion with GPS-IMU sensors

Carnegie Mellon University

Pittsburgh, Pennsylvania, USA

VISITING SCHOLAR, MACHINE LEARNING DEPARTMENT

May 17-Aug 17

Under the supervision of Katerina Fragkiadaki, worked on developing Ego-motion estimation for UAVs with low cost sensors (Monocular Camera, IMU) using Deep Learning Techniques. IMU sensor is used to overcome the problem of less or no visual correspondences during fast motion.

RESEARCH ASSOCIATE, FIELD ROBOTICS CENTER

Sept 15-April 16

Under the supervision of Sebastian Scherer, for the application of Industrial inspection with UAVs, I worked on system integration, control and real-time coverage planner to optimize flight time.

Publications

Social-STAGE: Spatio-Temporal Multi-Modal Future Trajectory Forecast

ICRA

INTERNATIONAL CONFERENCE ON ROBOTICS AND AUTOMATION

2021

[HTTPS://ARXIV.ORG/PDF/2011.04853.PDF](https://arxiv.org/pdf/2011.04853.pdf)

S Malla, B Dariush and C Choi

RAIN: Reinforced hybrid attention inference network for motion forecasting *ICCV*
INTERNATIONAL CONFERENCE ON COMPUTER VISION 2021
[HTTPS://ARXIV.ORG/PDF/2108.01316.PDF](https://arxiv.org/pdf/2108.01316.pdf)
J Li, F Yang, H Ma, [S Malla](#), M Tomizuka and C Choi

LOKI: Long Term and Key Intentions for Trajectory Prediction *ICCV*
INTERNATIONAL CONFERENCE ON COMPUTER VISION 2021
[HTTPS://ARXIV.ORG/PDF/2108.08236.PDF](https://arxiv.org/pdf/2108.08236.pdf)
H Girase*, H Gang*, [S Malla](#), J Li, A Kanehara, K Mangalam, C Choi

Shared Cross-Modal Trajectory Prediction for Autonomous Driving *CVPR "ORAL"*
COMPUTER VISION AND PATTERN RECOGNITION 2021
[HTTPS://ARXIV.ORG/PDF/2011.08436.PDF](https://arxiv.org/pdf/2011.08436.pdf)
C Choi, J H Choi, J Li, [S Malla](#)

Bird's Eye View Segmentation Using Lifted 2D Semantic Features *BMVC*
BRITISH MACHINE VISION CONFERENCE 2021
[HTTPS://WWW.BMVC2021-VIRTUALCONFERENCE.COM/ASSETS/PAPERS/0772.PDF](https://www.bmvc2021-virtualconference.com/assets/papers/0772.pdf)
I Dwivedi, [S Malla](#), YT Chen, B Dariush

DROGON: A Trajectory Prediction Model based on Intention-Conditioned Behavior Reasoning *CoRL*
CONFERENCE ON ROBOT LEARNING 2020
[HTTPS://ARXIV.ORG/PDF/1908.00024.PDF](https://arxiv.org/pdf/1908.00024.pdf)
C Choi, [S Malla](#), A Patil, J H Choi

TITAN: Future Forecast using Action Priors *CVPR "ORAL"*
COMPUTER VISION AND PATTERN RECOGNITION 2020
[HTTPS://ARXIV.ORG/PDF/2003.13886.PDF](https://arxiv.org/pdf/2003.13886.pdf)
[S Malla](#), B Dariush and C Choi

SSP: Single Shot Future Trajectory Prediction *IROS*
INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS 2020
[HTTPS://ARXIV.ORG/PDF/2004.05846.PDF](https://arxiv.org/pdf/2004.05846.pdf)
I Dwivedi, [S Malla](#), B Dariush, C Choi

The H3D Dataset for Full-Surround 3D Multi-Object Detection and Tracking in Crowded Urban Scenes *ICRA*
INTERNATIONAL CONFERENCE ON ROBOTICS AND AUTOMATION 2019
[HTTPS://ARXIV.ORG/PDF/1903.01568.PDF](https://arxiv.org/pdf/1903.01568.pdf)
A Patil, [S Malla](#), H Gang, Y T Chen

Development of an intelligent pressure measuring technique for bellows using radial basis function neural network *Elsevier*
SENSORS AND ACTUATORS A: PHYSICAL 2016
[HTTPS://WWW.SCIENCEDIRECT.COM/SCIENCE/ARTICLE/ABS/PII/S0924424715302697](https://www.sciencedirect.com/science/article/abs/pii/S0924424715302697)
V Naveen, V Komanapalli, and [S Malla](#)

Gesture Control Interface Using Machine Learning Algorithms *IJARCSSE*
IJARCSSE VOLUME 5, ISSUE. 09 (2015) ISSN: 2277-128X. 2015
[HTTPS://WWW.RESEARCHGATE.NET/PUBLICATION/291559092_GESTURE_CONTROL_INTERFACE_USING_MACHINE_LEARNING_ALGORITHMS](https://www.researchgate.net/publication/291559092_Gesture_Control_Interface_Using_Machine_Learning_Algorithms)
H S Baweja, T Parhar, [S Malla](#)

NEMO: Future Object Localization Using Noisy Ego Priors *ITSC*
INTERNATIONAL CONFERENCE ON INTELLIGENT TRANSPORTATION SYSTEMS 2022
[HTTPS://ARXIV.ORG/PDF/1909.08150.PDF](https://arxiv.org/pdf/1909.08150.pdf)
[S Malla](#), I Dwivedi, B Dariush, C Choi

DRAMA: Joint Risk Localization and Captioning in Driving

ACCEPTED TO WINTER CONFERENCE ON APPLICATIONS OF COMPUTER VISION

WACV

2023

[S Malla](#), C Choi, J H Choi, I Dwivedi, and J Li

Papers under review

CLR-GAM: Contrastive Point Cloud Learning with Guided Augmentation and Feature Mapping

SUBMITTED TO NEURAL INFORMATION PROCESSING SYSTEMS

[S Malla](#), Y chen

Trajectory Prediction by Clustering Human Interactions at Multiple Scales

C Choi*, D Lee*, [S Malla](#), S Bae, and J Kim

Patents

System and method for future forecasting using action priors

US PATENT APP. 16/913,260

[Srikanth Malla](#), Chiho Choi, Behzad Dariush

ACCEPTED

2021

Systems and methods for providing future object localization

US PATENT APP. 16/828,343

[Srikanth Malla](#), Chiho Choi

ACCEPTED

2021

Composite field based single shot prediction

US PATENT APP. 16/917,864

Isht Dwivedi, Chiho Choi, [Srikanth Malla](#), Behzad Dariush

ACCEPTED

2021

SYSTEM AND METHOD FOR PROVIDING SOCIAL-STAGE SPATIO-TEMPORAL MULTI-MODAL FUTURE FORECASTING

US PATENT APP.17/160,747

[Srikanth Malla](#), Chiho Choi, Behzad Dariush

ACCEPTED

2021

SYSTEM AND METHOD FOR COMPLETING TRAJECTORY PREDICTION FROM AGENT-AUGMENTED ENVIRONMENTS

US PATENT APP. 17/161,136

Chiho Choi, [Srikanth Malla](#), Sangjae Bae

ACCEPTED

2021

System and method for completing Joint Risk Localization and Reasoning in Driving

US PATENT APP. 17/388,256

[Srikanth Malla](#)

FILED

2021

SYSTEM AND METHOD FOR PROVIDING LONG TERM AND KEY INTENTIONS FOR TRAJECTORY PREDICTION

US PATENT APP. 17/352,540

Harshayu Vishwajeet Girase, Haiming Gang, [Srikanth Malla](#), Jiachen Li, Akira Kanehara, Chiho Choi

FILED

2021

System and method for automated extrinsic calibration of Lidars, Cameras, Radars, and Ultrasonic Sensors on Vehicles and Robots

PROVISIONAL FILED

Nikhil Naikal, Alexander Marques, [Srikanth Malla](#)

FILED

2021

Technical Skills

Programming Python, C++, Matlab
ML Frameworks PyTorch, TensorFlow, Keras, CUDA
Vision Libraries PCL, OpenCV
Robotics Frameworks OpenRave, , Multisim, ROS, Solid Works, MoveIt, Gazebo, MuJoCo
Robots: Baxter, UAVs (custom built, DJI), Kuka Youbot, Turtle Bot
Others Linux, Docker, Vim, IPythonNotebook, Google Colab, Git, Github, AWS S3, AWS EC2, \LaTeX

Editorial Service

2022	WACV , Winter Conference on Applications of Computer Vision	<i>Reviewer</i>
2022	ECCV , European Conference on Computer Vision	<i>Reviewer</i>
2022	CVPR , Computer Vision and Pattern Recognition	<i>Reviewer</i>
2022	RAL , Robotics and Automation Letters	<i>Reviewer</i>
2021	ICCV , International Conference on Computer Vision (MAIR2 Workshop)	<i>Reviewer</i>
2021-22	ICRA , International Conference on Robotics and Automation	<i>Reviewer</i>
2020	IROS , International Conference on Intelligent Robots and Systems	<i>Reviewer</i>
2020	IJRR , International Journal of Robotics Research	<i>Reviewer</i>
2020	T-IV , Transactions on Intelligent Vehicles	<i>Reviewer</i>

Teaching

Worcester Polytechnic Institute

ELECTRICAL AND COMPUTER ENGINEERING DESIGN, ECE 2799

In Spring 2017, I was the tutor for the course ECE 2799. Half of the course is project based and I supervised the electronics projects.

Tutor

Spring 2017

Teaching Assistant

SYNERGY OF HUMAN AND ROBOTIC SYSTEMS, RBE 595

In Fall 2017 I was the Teaching Assistant for the course RBE 595, which is an advanced course designed for project-based robot design. I was part of grading the students assignments and tests. And help the students with questions in the class.

Fall 2017

Honors and Awards

Ministry of Human Resource and Development, India

MERIT SCHOLARSHIP

2013, 2014

Study Abroad Scholarship, India

VIDESHI VIDYA DEVANA, ANDHRA PRADESH STATE SPONSORED SCHOLARSHIP

2017

Media Coverage

LOKI: An intention data set to train models for pedestrian and vehicle trajectory prediction

[HTTPS://TECHXPLORE.COM/NEWS/2021-09-LOKI-INTENTION-DATASET-PEDESTRIAN-VEHICLE.HTML](https://techxplore.com/news/2021-09-loki-intention-dataset-pedestrian-vehicle.html)

Tech Xplore

September 9, 2021